

EAST Search History

EAST Search History (Prior Art)

| Ref # | Hits | Search Query | DBs | Default Operator | Plurals | Time Stamp |
|-------|-------|---|---|------------------|---------|---------------------|
| S1 | 56205 | (obstacle object) with (bubble area zone threshold) same (detection detecting recognition setting) | US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB | OR | ON | 2010/05/20 18:26 |
| S2 | 19575 | (obstacle object) with (bubble area zone threshold) same (detection detecting recognition setting) and ((optical video image) with (recognition detect\$3 sens \$3)) and (edge distance intersection) | US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB | OR | ON | 2010/05/20 18:28 |
| S3 | 6397 | (obstacle object) with (bubble area zone threshold) same (detection detecting recognition setting) and ((optical video image) with (recognition detect\$3 sens \$3)) and (edge distance intersection) and (buffer warning safe danger) | US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB | OR | ON | 2010/05/20 18:30 |
| S4 | 5060 | (obstacle object) with (bubble area zone threshold) same (detection detecting recognition setting) and ((optical video image) with (recognition detect\$3 sens \$3)) and (edge distance intersection) and ((buffer warning safe danger margin passive) with (buffer zone area bubble threshold degree)) | US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB | OR | ON | 2010/05/20 18:31 |
| S5 | 429 | (obstacle object) with (bubble area zone threshold) same (detection detecting recognition setting) and ((optical video image) with (recognition detect\$3 sens \$3)) and (edge distance intersection) and ((buffer warning safe danger margin passive) with (buffer zone area bubble threshold degree)) and robot | US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB | OR | ON | 2010/05/20 18:32 |
| S6 | 131 | (obstacle object) same (bubble area zone distance threshold) same (detection detecting recognition setting) and ((buffer warning safe danger margin passive) with (buffer zone area bubble threshold degree)) and (700/245,258,259).ccls. | US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB | OR | ON | 2010/05/21 11:24 |
| S7 | 455 | (obstacle object) same (bubble area zone distance threshold) same (detection detecting recognition setting) and ((buffer warning safe danger margin passive) with (buffer zone area bubble threshold degree)) and (701/23,25,28,211,301,302).ccls. | US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB | OR | ON | 2010/05/21 12:03 |

5/ 21/ 2010 6:13:18 PM

C:\Documents and Settings\skong\My Documents\EAST Workspaces\10538523 20100520 Robot Control

Device, Robot Control method and program.wsp